

# Rapid Hand-held Scanning for Corrosion Imaging

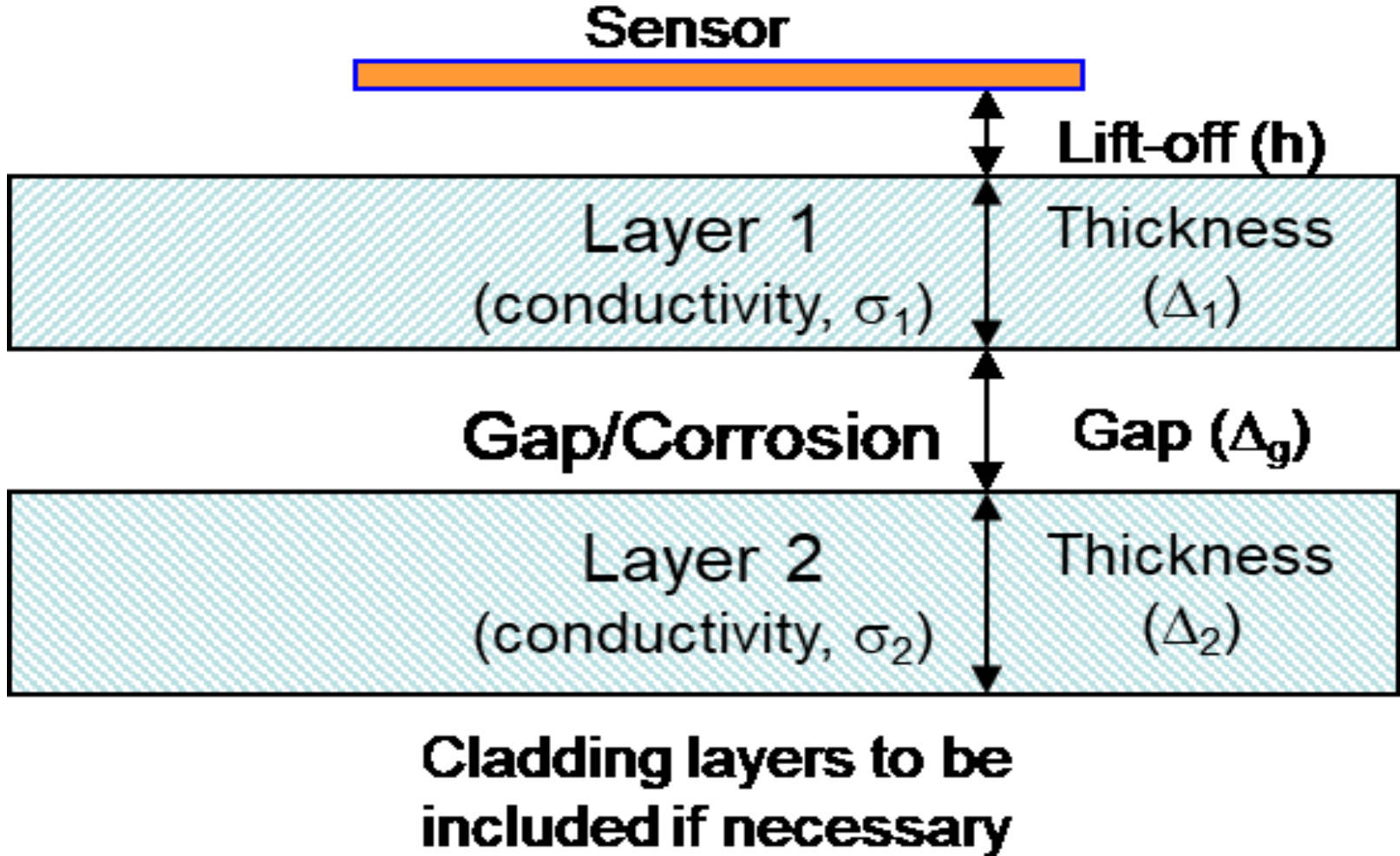
AA&S 2019

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Karen Diaz, Jared Nelms, Zachary Thomas, Neil Goldfine

JENTEK Sensors, Inc., 121 Bartlett Street, MA 01752



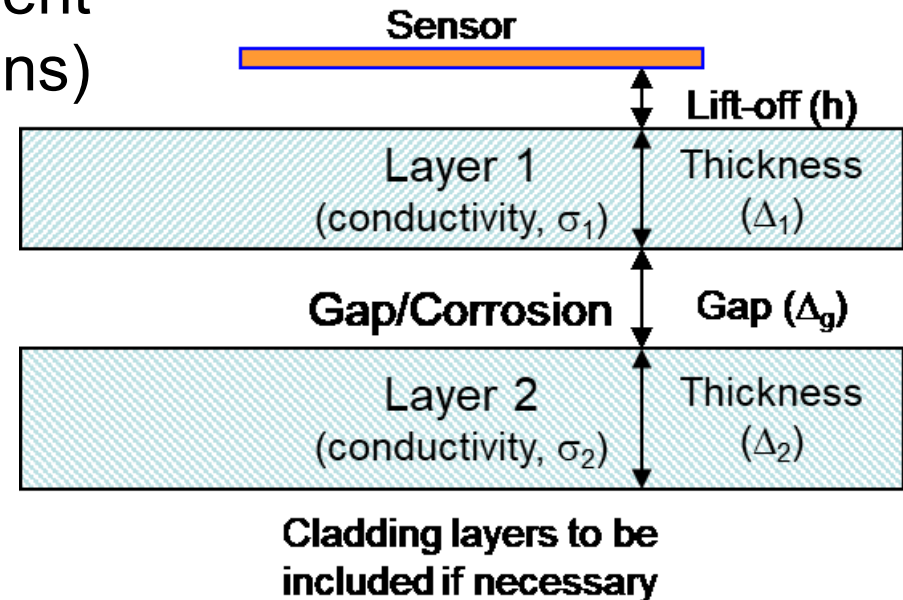
# Aircraft Joint Problem Description



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## Prior Work

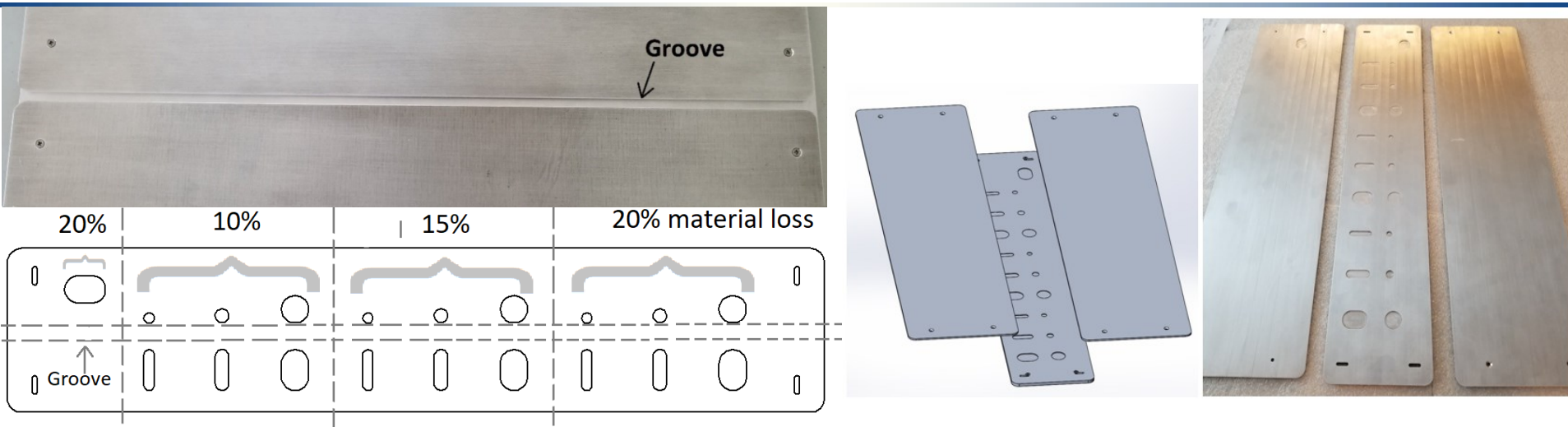
- 2003 Demonstrated independent measurement of (0.040 in. skins)
  - 1<sup>st</sup> layer thickness
  - 2<sup>nd</sup> layer thickness
  - Gap
  - Liftoff (paint thickness)
- Limitations in 2003 Work
  - Slow
  - High cost of systems
  - Limited portability of systems



## Goal of ongoing work (thicker layers)

- Scan speed 1 inch per second
- jET for improved portability (<1 pound plus tablet computer)
- GS8200 for wider scans (<15 pounds plus tablet computer)
- Easily adaptable to new and thicker applications (jAI)

# Simple Joint Sample with Material Loss Areas



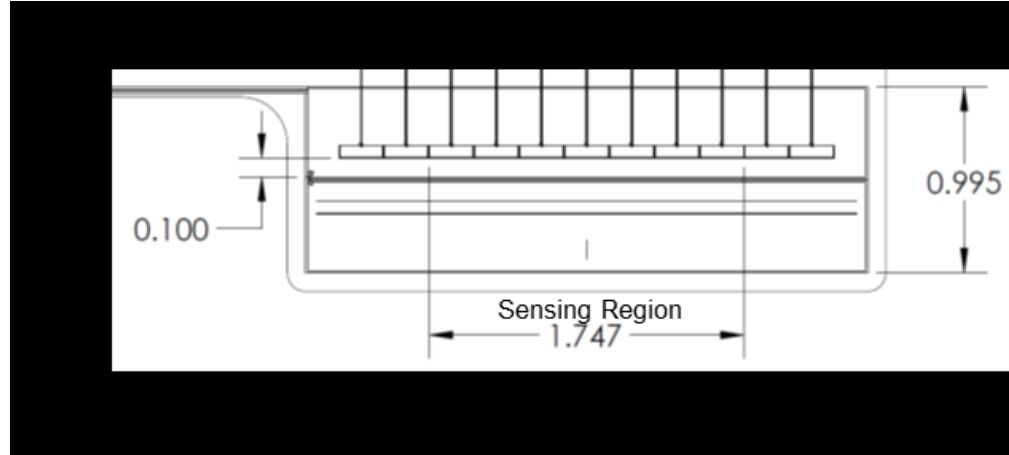
- Two upper layers (skin) over top of a single lower layer (spar)
- The upper layers form a “groove” over the lower layer that can be adjusted to different widths.
- The lower layer contains simulated corrosion defects of varying shape and percent material loss depths.

# jET with MWM-Array Technology

**jET**



**MWM-Array**



- jET
  - 3 frequencies simultaneously
  - 7 channels simultaneously
  - Up to 1000 measurements/sec per channel
- MWM-Array
  - Designed for model based inverse methods
  - Drive sense gap determines depth of penetration



# MWM-Array Technology - Depth of Penetration

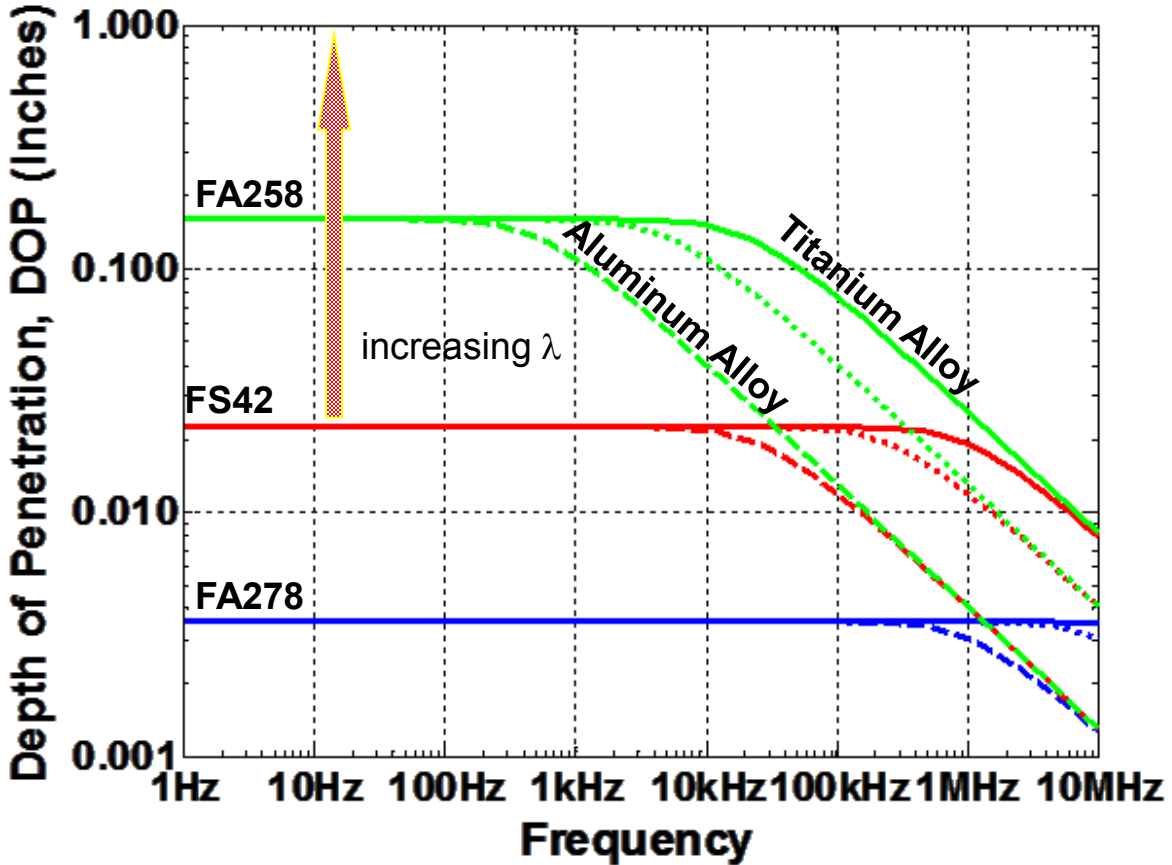
Field Variation with Depth  $\approx e^{-\Gamma_n z}$

$$\Gamma_n = \sqrt{(2\pi n / \lambda)^2 + j2 / \delta^2}$$

Spatial Fourier Mode Depth of Penetration =  $1/\text{Re}(\Gamma_n)$

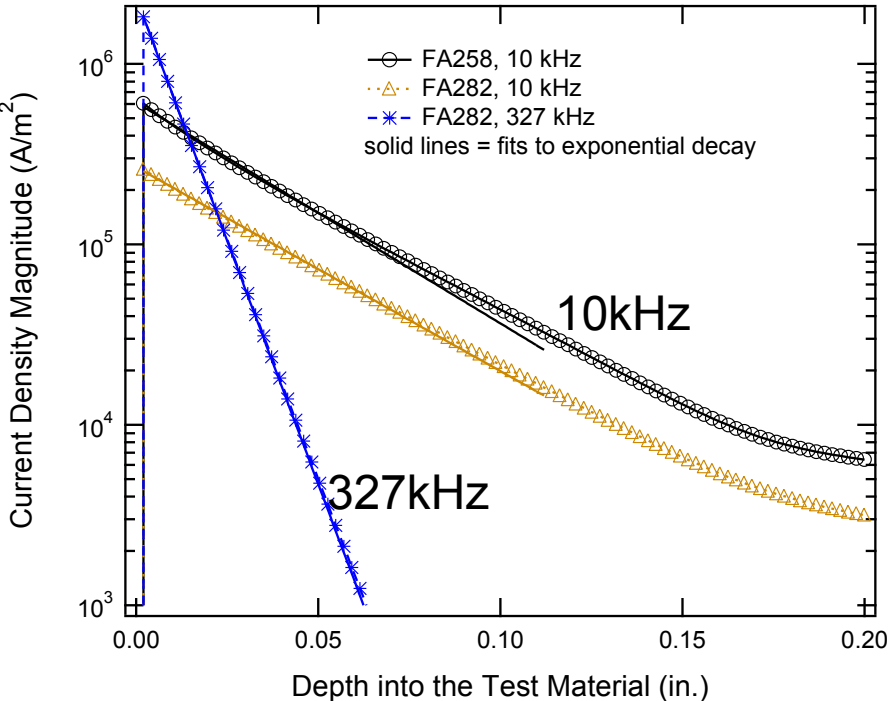
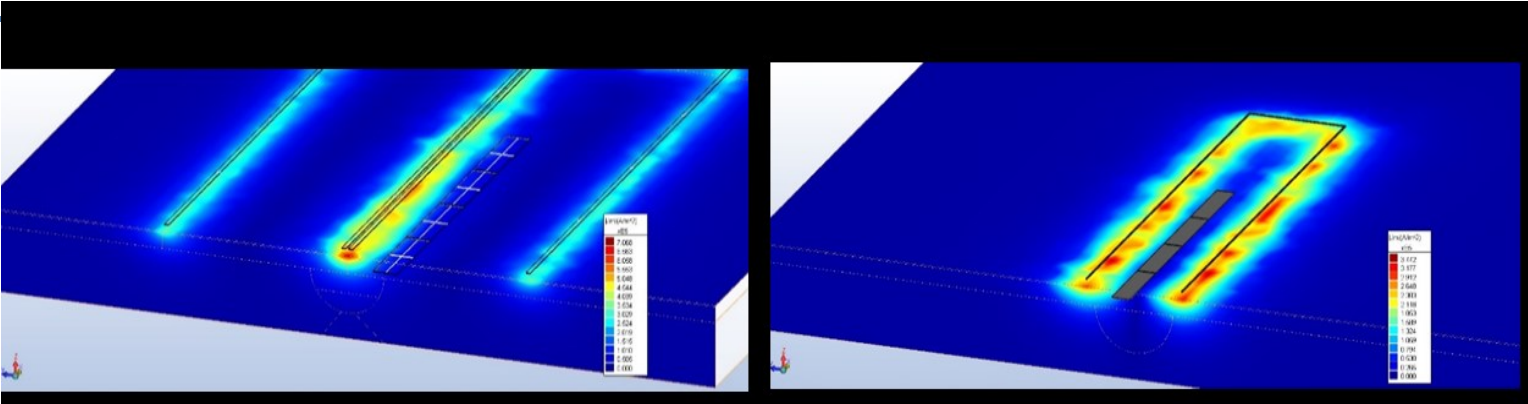
Low frequency asymptote =  $\lambda/2\pi$

Skin depth:  $\delta = \sqrt{\frac{1}{\pi f \mu \sigma}}$





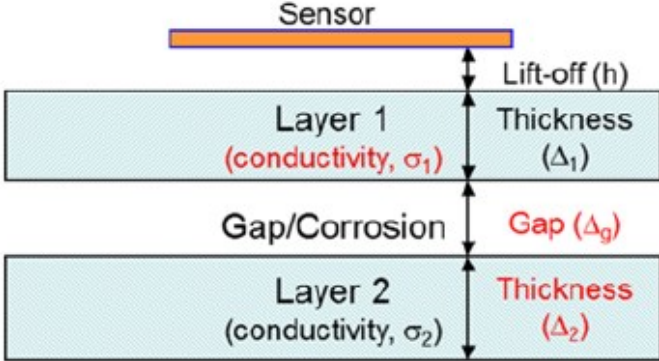
# MWM-Array Induced Eddy Currents



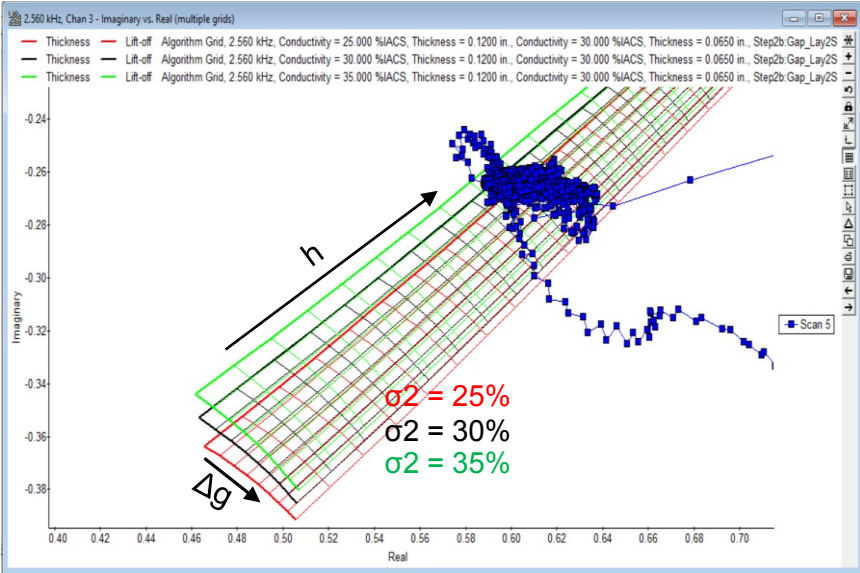
- Upper images show the baseline material responses.
- Left plot shows the current density magnitude under the drive windings of the MWM-Arrays.

# Model Based Multivariate Inverse Methods (MIMs)

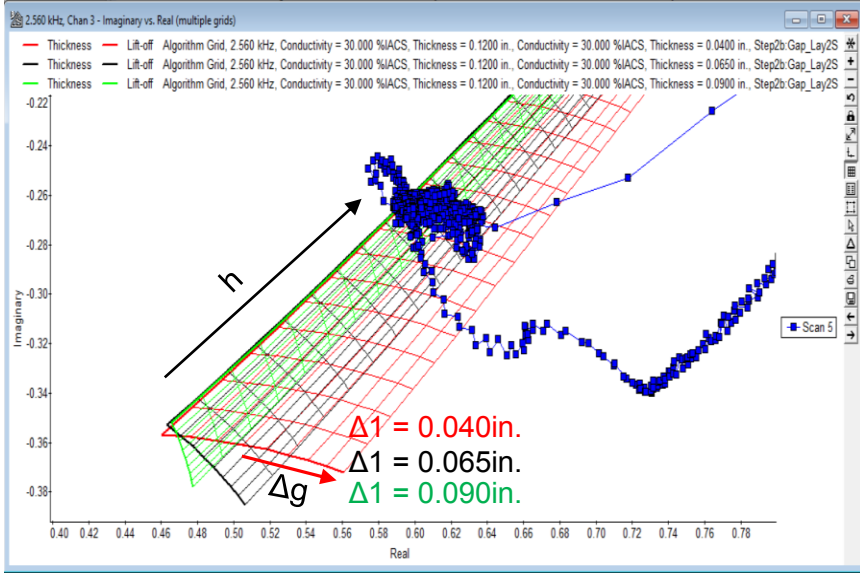
- Lattice is collection of 2-D grids (sensor response surfaces)
- Single frequency can estimate up to two unknowns
- Two frequencies can estimate up to four unknowns, etc.



2.56 kHz  $\Delta_g$  -h Lattice  
(Layer 2 Conductivity varied)

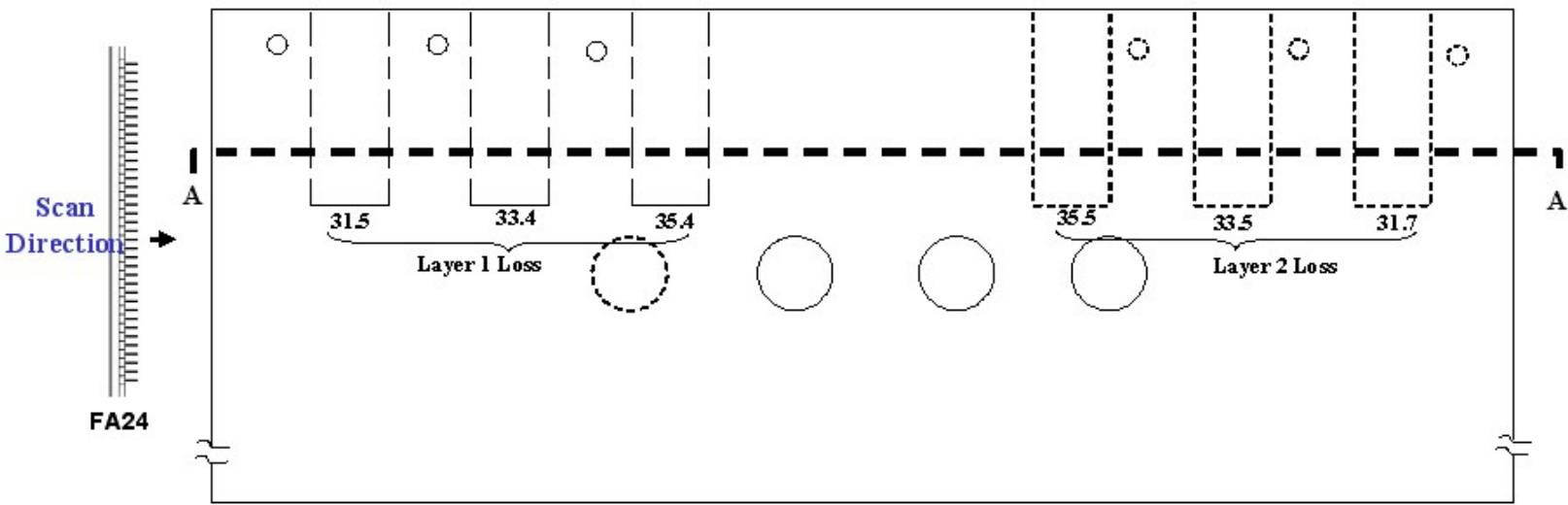


2.56 kHz  $\Delta_g$  -h Lattice  
(Layer 1 Thickness varied)

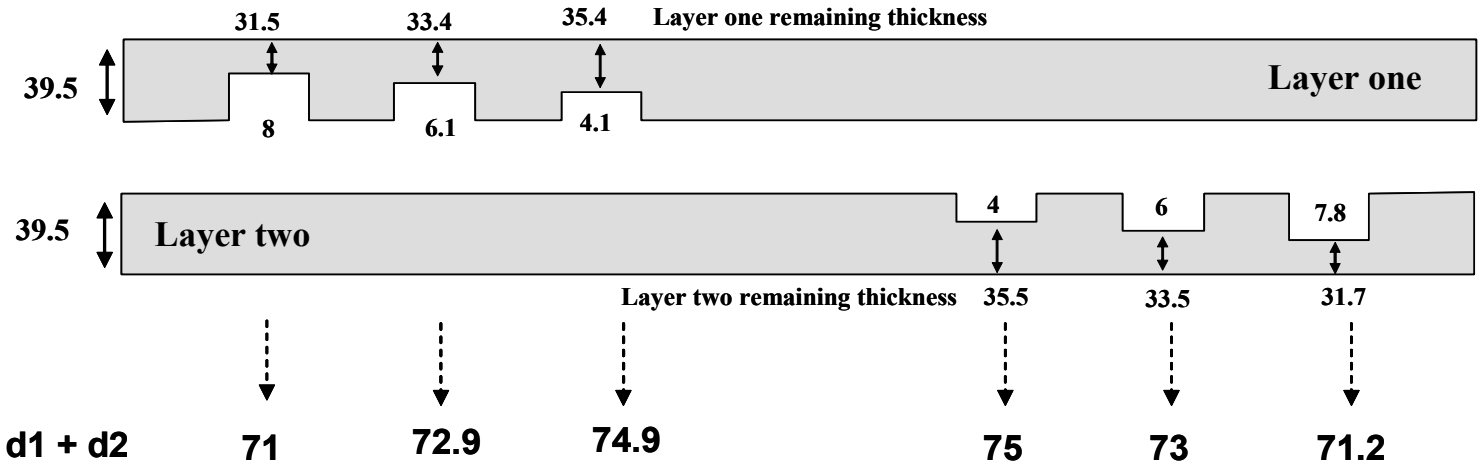




# 2003 Results on Air Force Material Loss Standard (1)

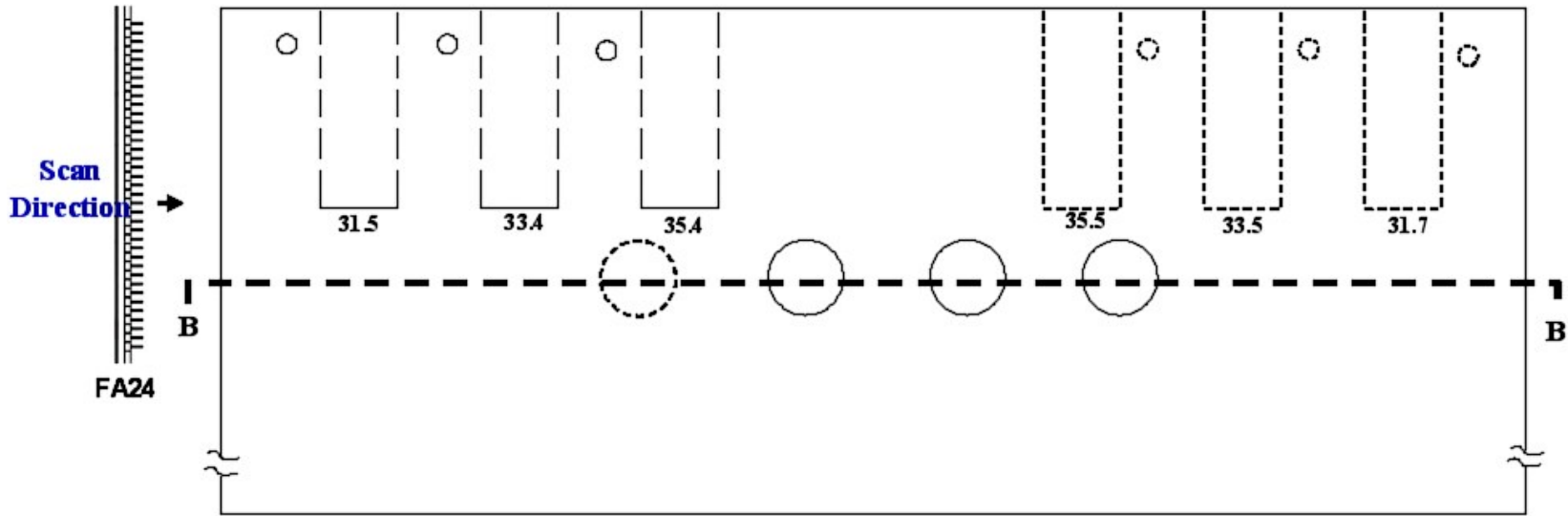


**A-A Cross Section**

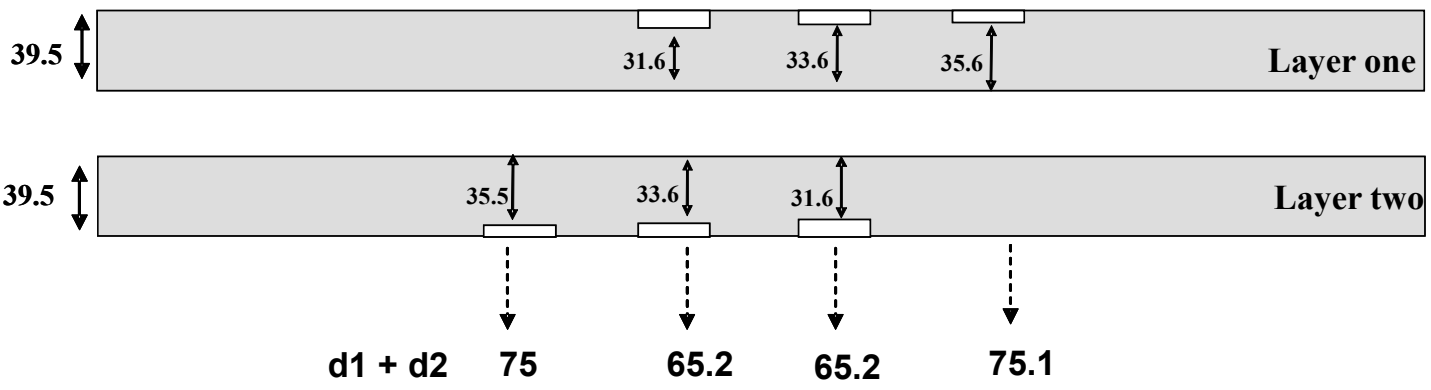


Dimensions in Mils (1 mil = 0.001 in.)

# 2003 Results on Air Force Material Loss Standard (2)



## B-B Cross Section

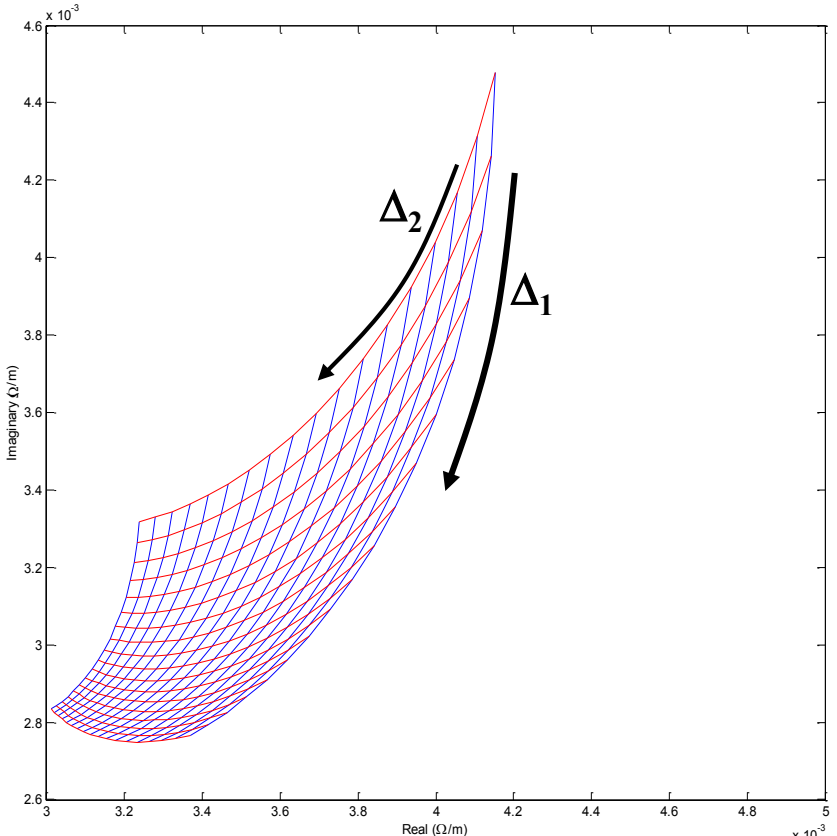


Dimensions in Mils (1 mil = 0.001 in.)

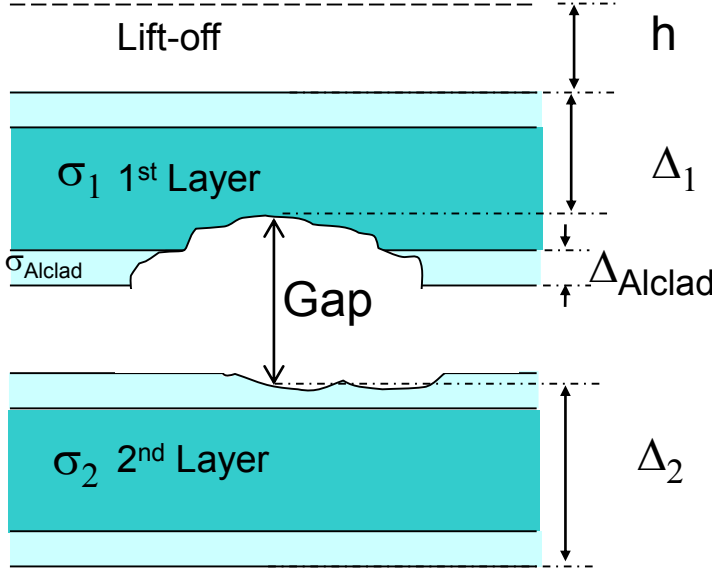
# Model Based Multivariate Inverse Methods (MIMs)

## 1<sup>st</sup> Layer Loss vs. 2<sup>nd</sup> Layer Loss

Example Measurement Grid at 10 kHz for a Gap of 0.011 in.

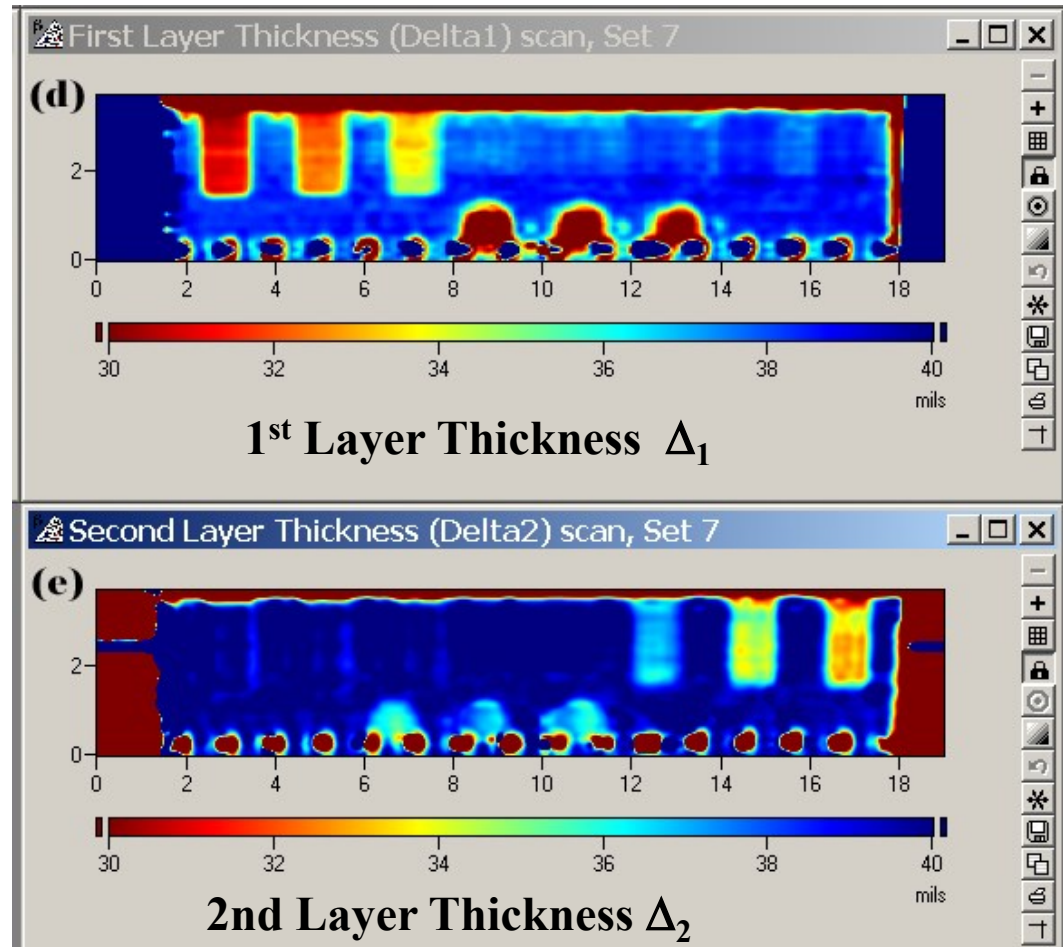
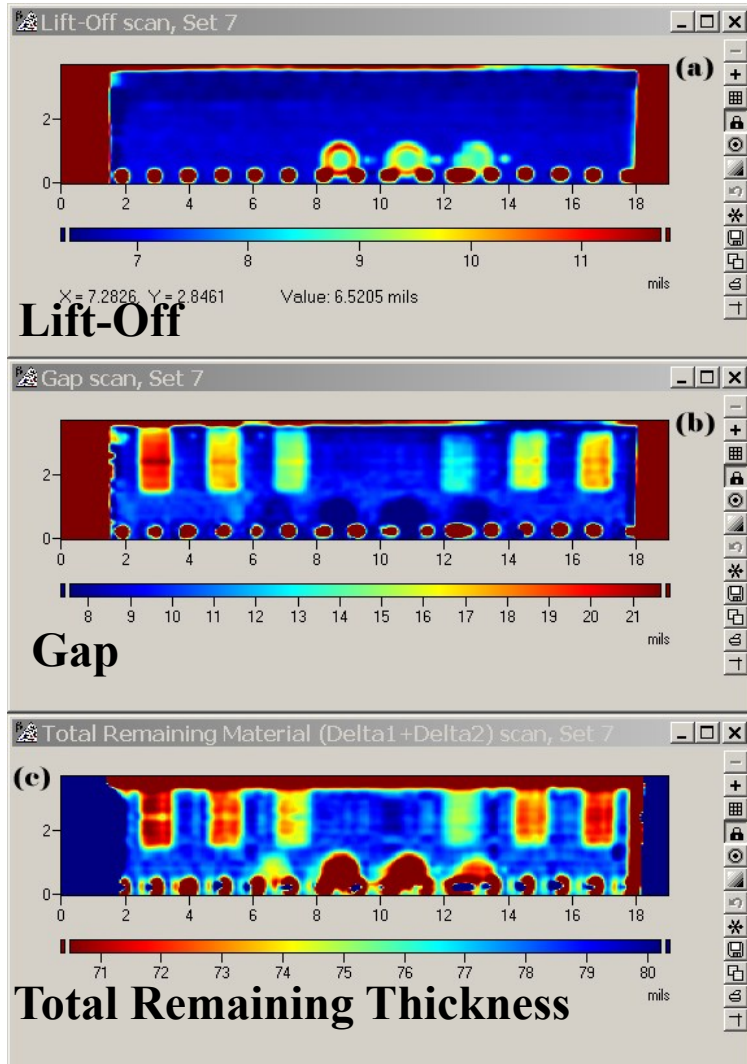


gap of 11 mils



# 2003: Results for 4-Unknown Results $h$ , $\Delta_1$ , $\Delta_2$ , Gap

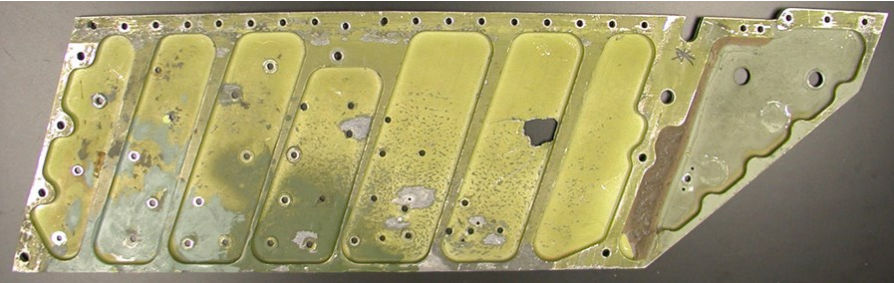
Independent 1<sup>st</sup> and 2<sup>nd</sup> layer loss imaging independent of gap



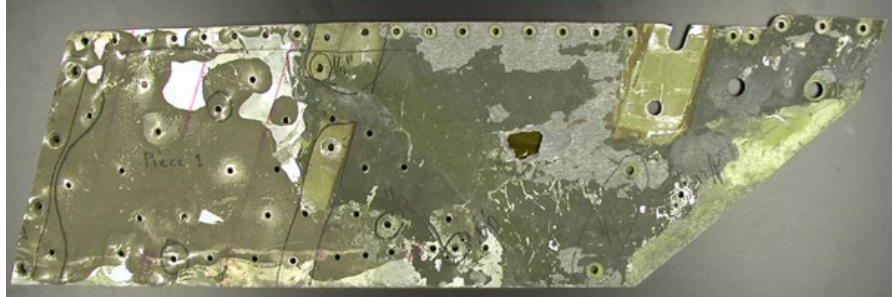


# 2003: Internal Geometric Feature and Hidden Damage Imaging: C-130 Flight Deck Chine Plate

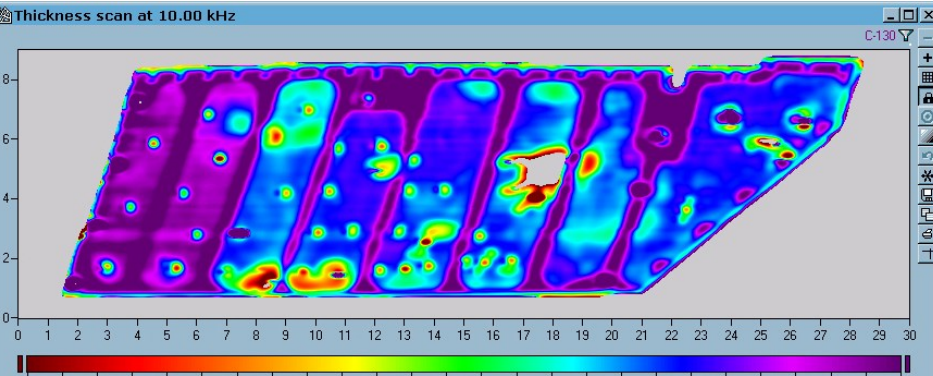
Inaccessible Side



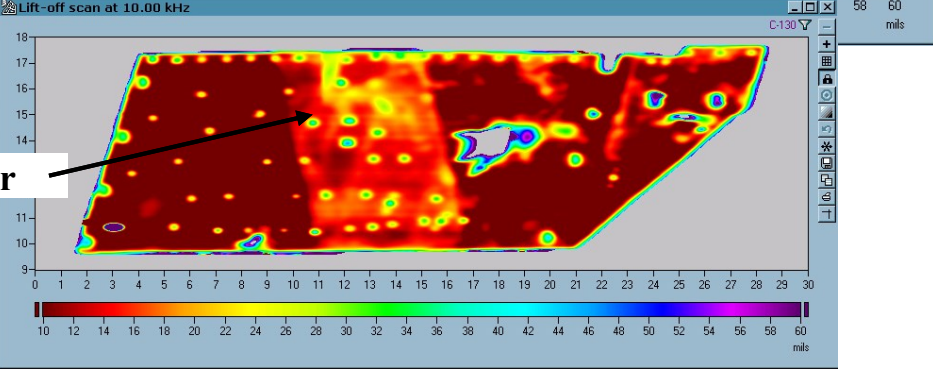
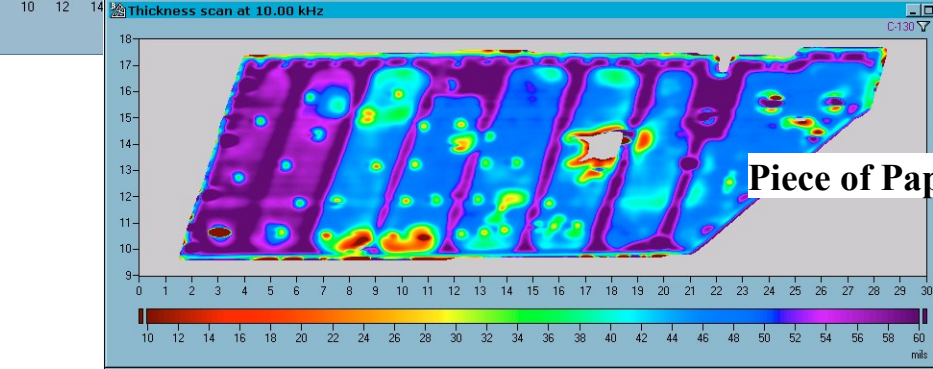
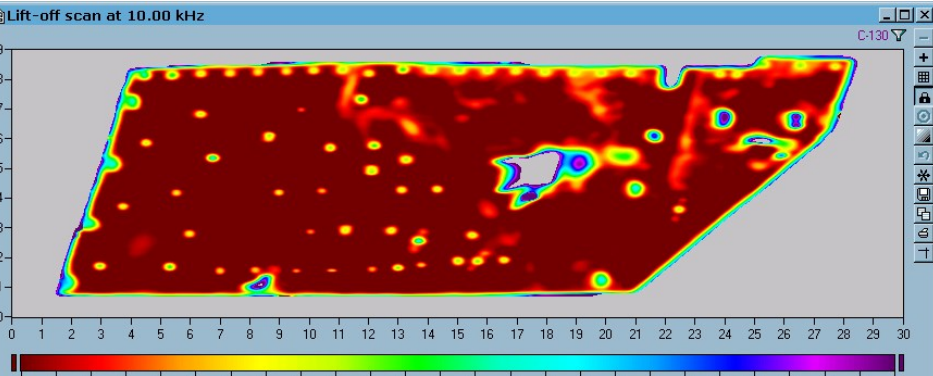
Accessible Side



Thickness Image from Accessible Side



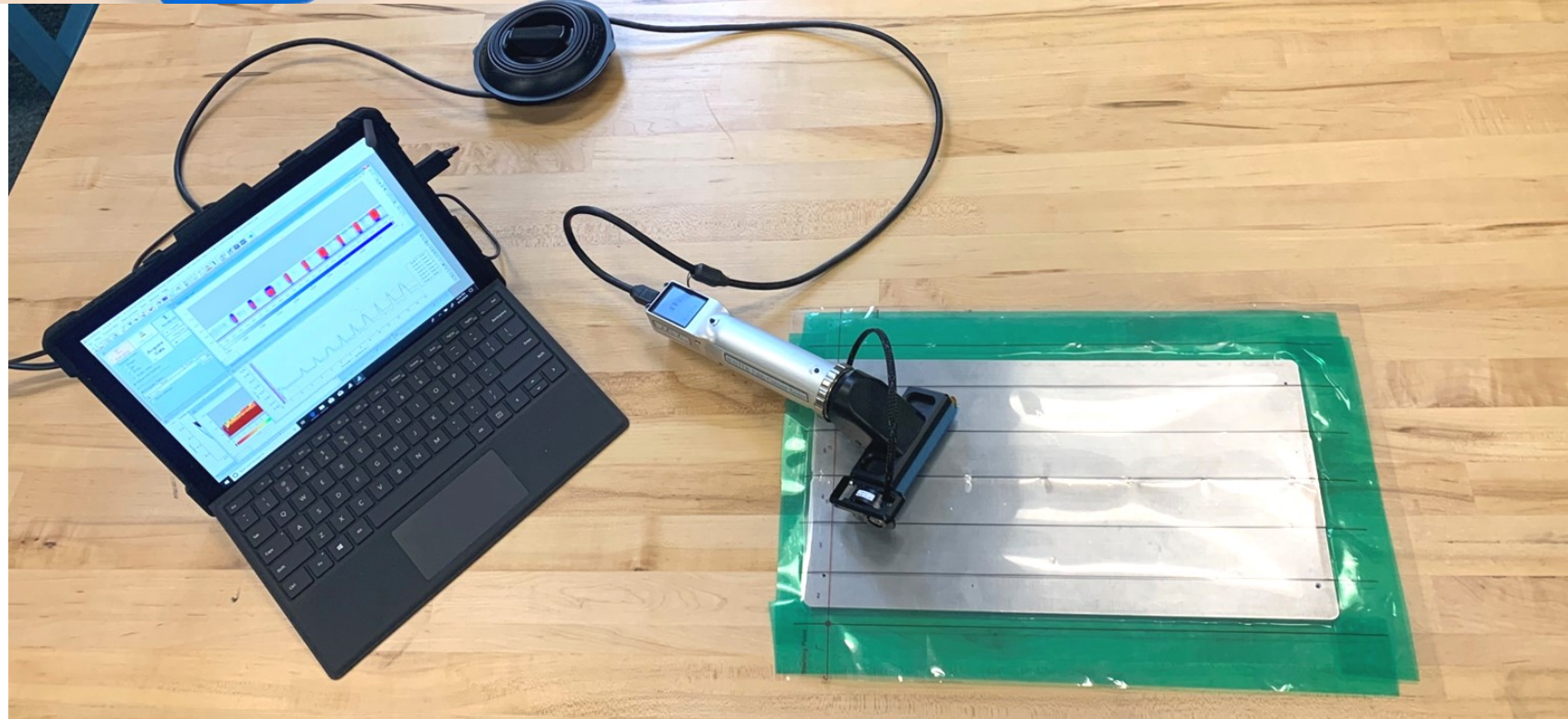
Surface Topology Image



Piece of Paper

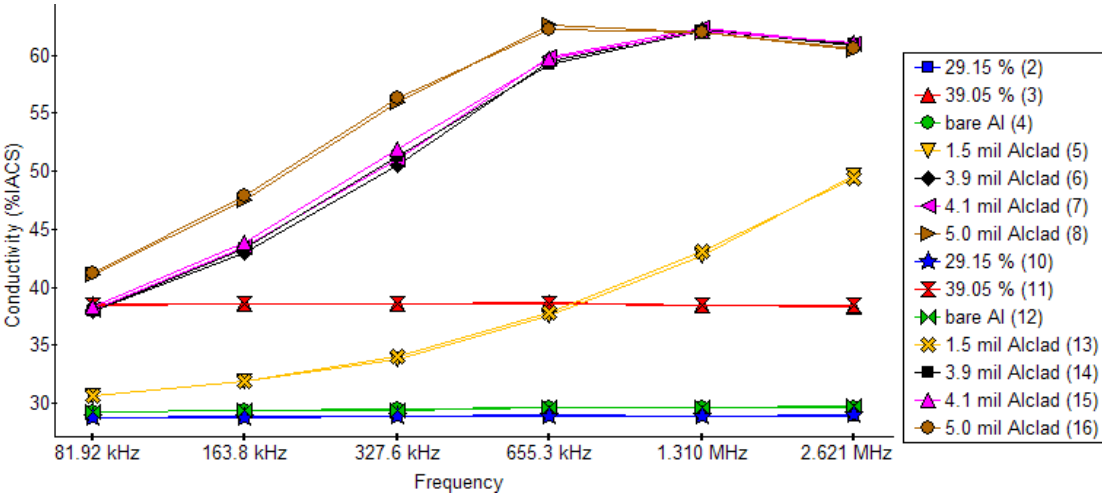


# New jET Hand Held 7-Channel System

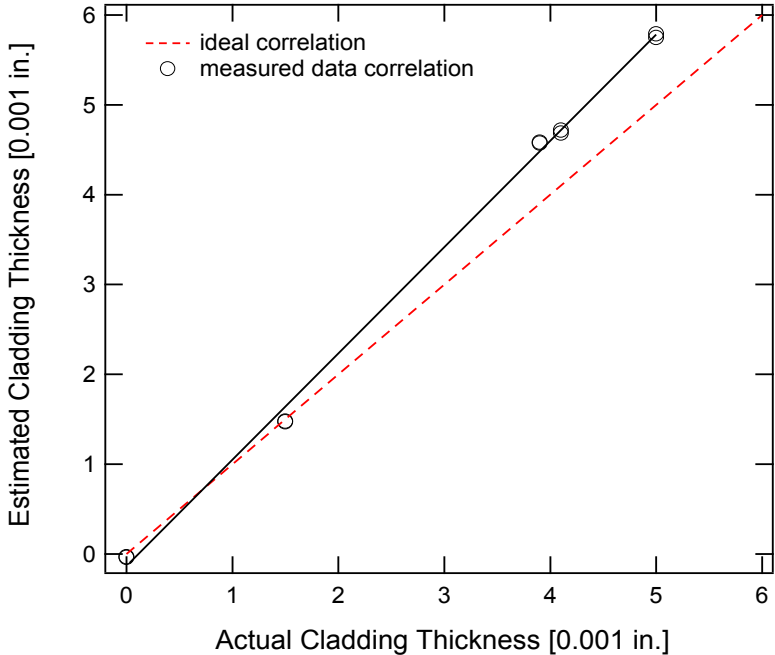


# Cladding Thickness Assessment

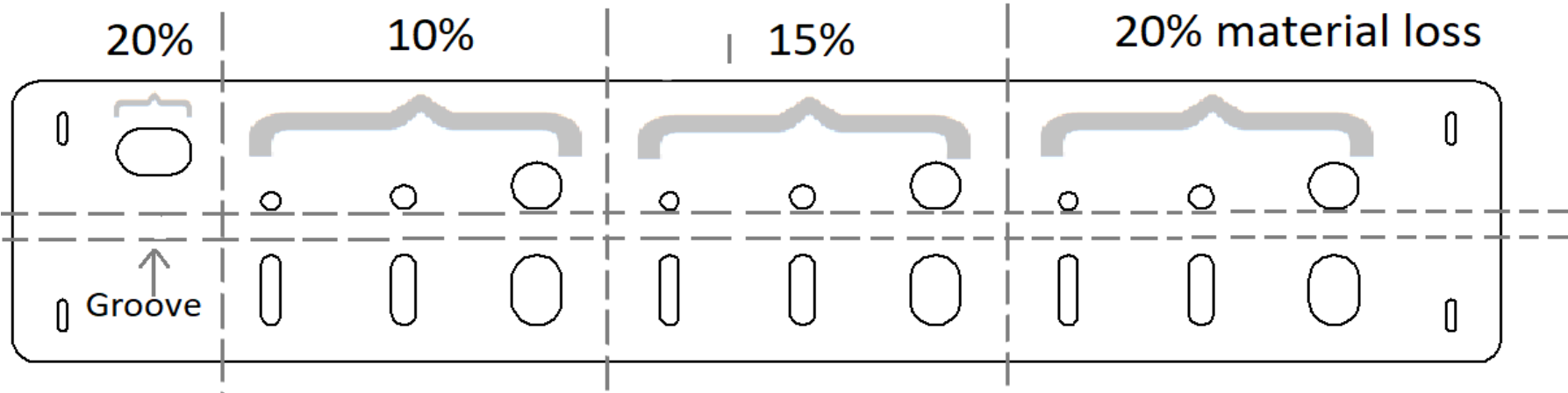
- Top: Effective conductivity values for FS42 measurements on several clad test coupons and several uncoated aluminum alloy samples.
- Bottom: Comparison of estimated and actual cladding



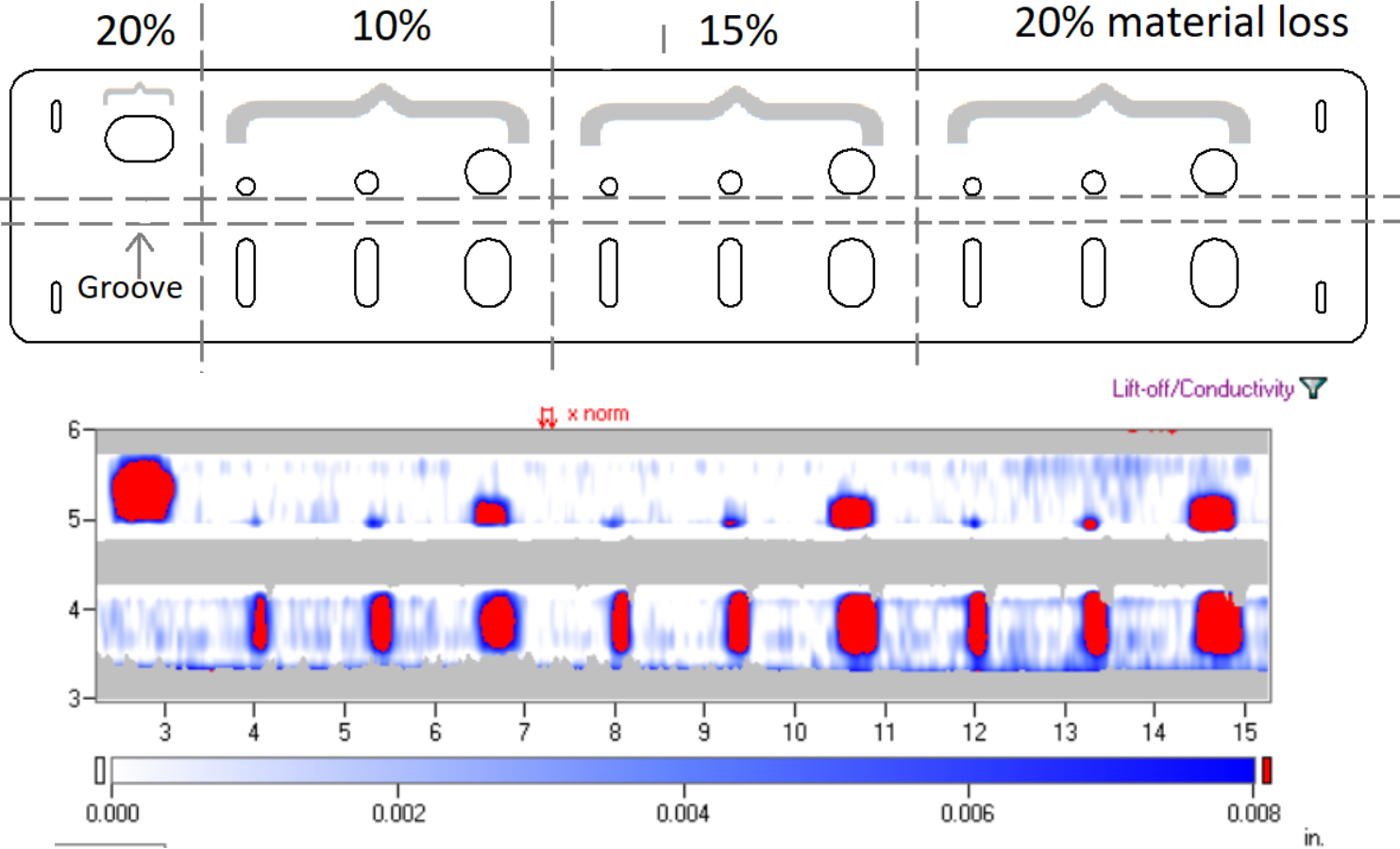
MWM



# 15 inch Corrosion Loss Sample

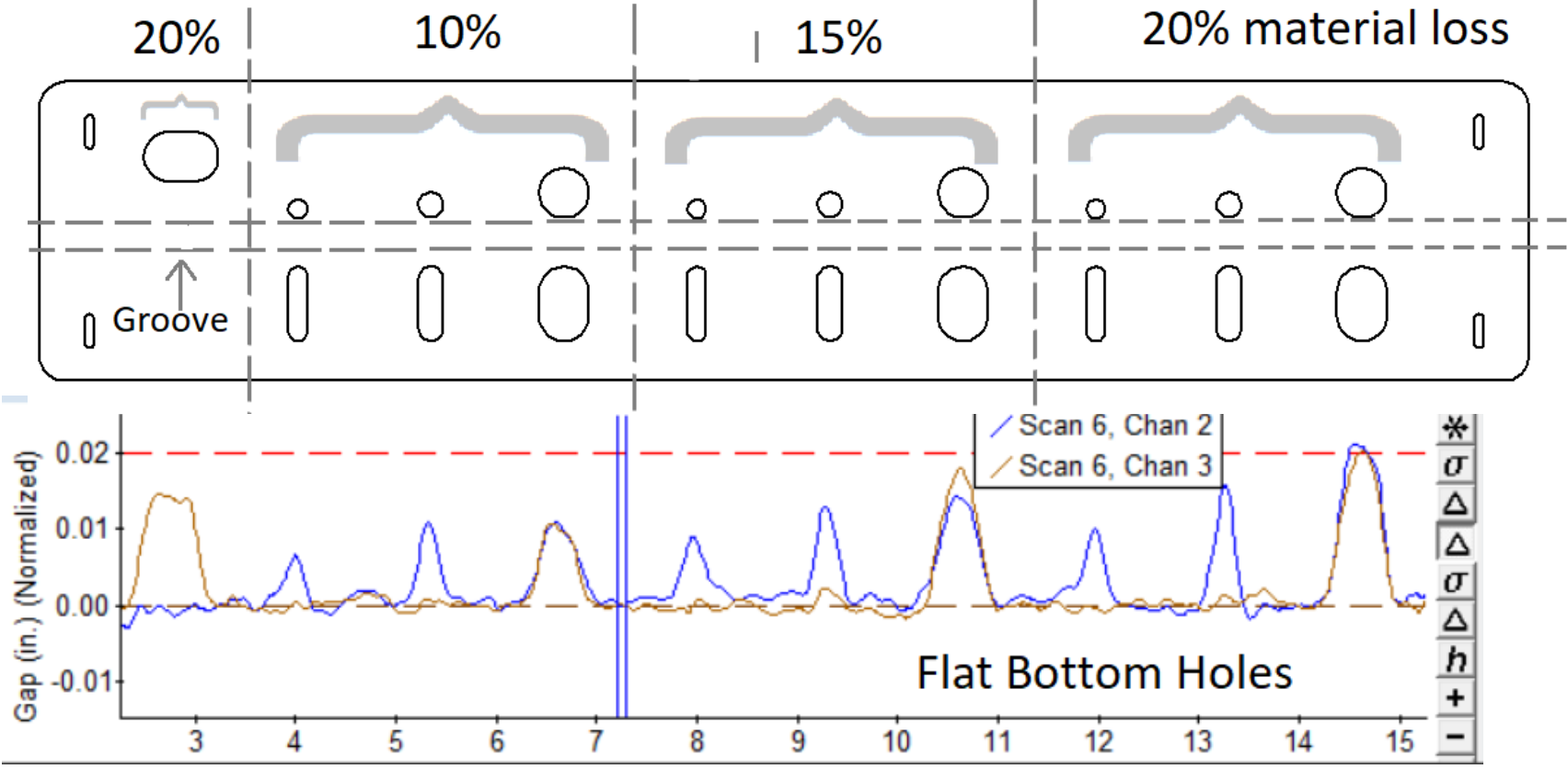


# FA258: 15 inch Corrosion Loss Sample (1)



- Filtered and normalized C-scan of Gap data across the corrosion defect locations.

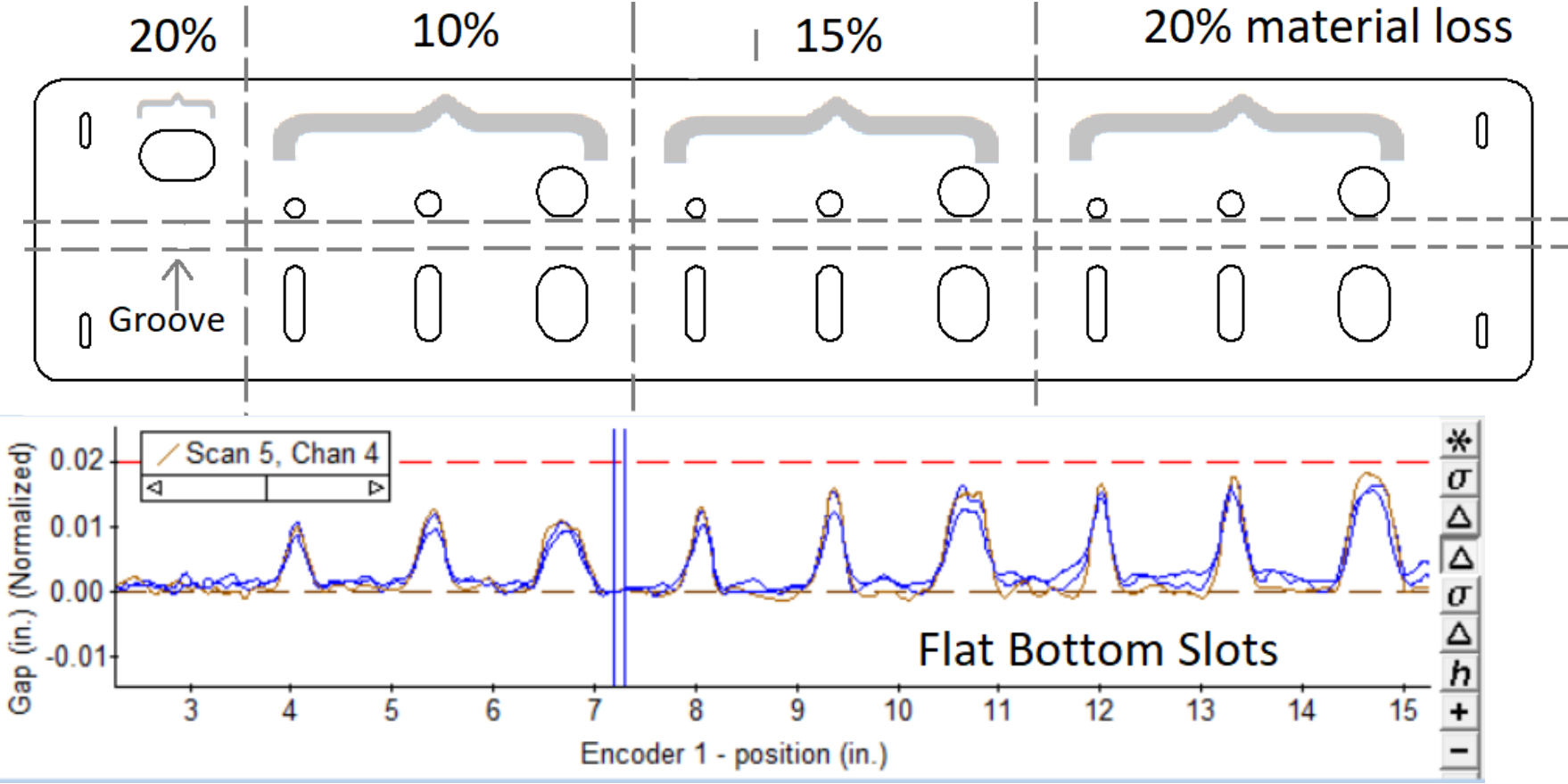
# FA258: 15 inch Corrosion Loss Sample Holes (2)



- Normalized B-scan of Gap data across the flat bottom hole defect locations.



# FA258: 15 inch Corrosion Loss Sample Slots (3)



- Normalized B-scan of Gap data across the flat bottom slot defect locations.

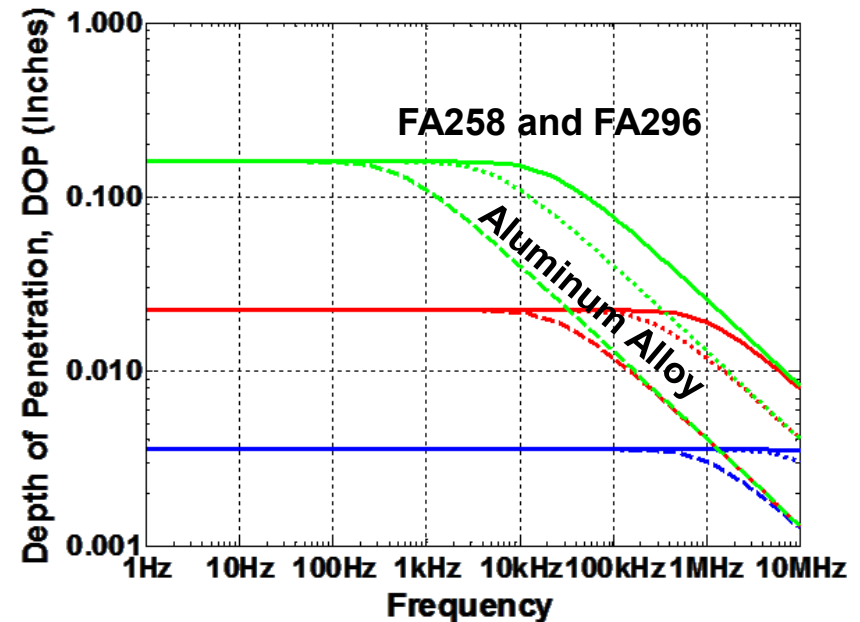
# New MWM-Array Sensor FA296

## First Prototype Sensor Capability

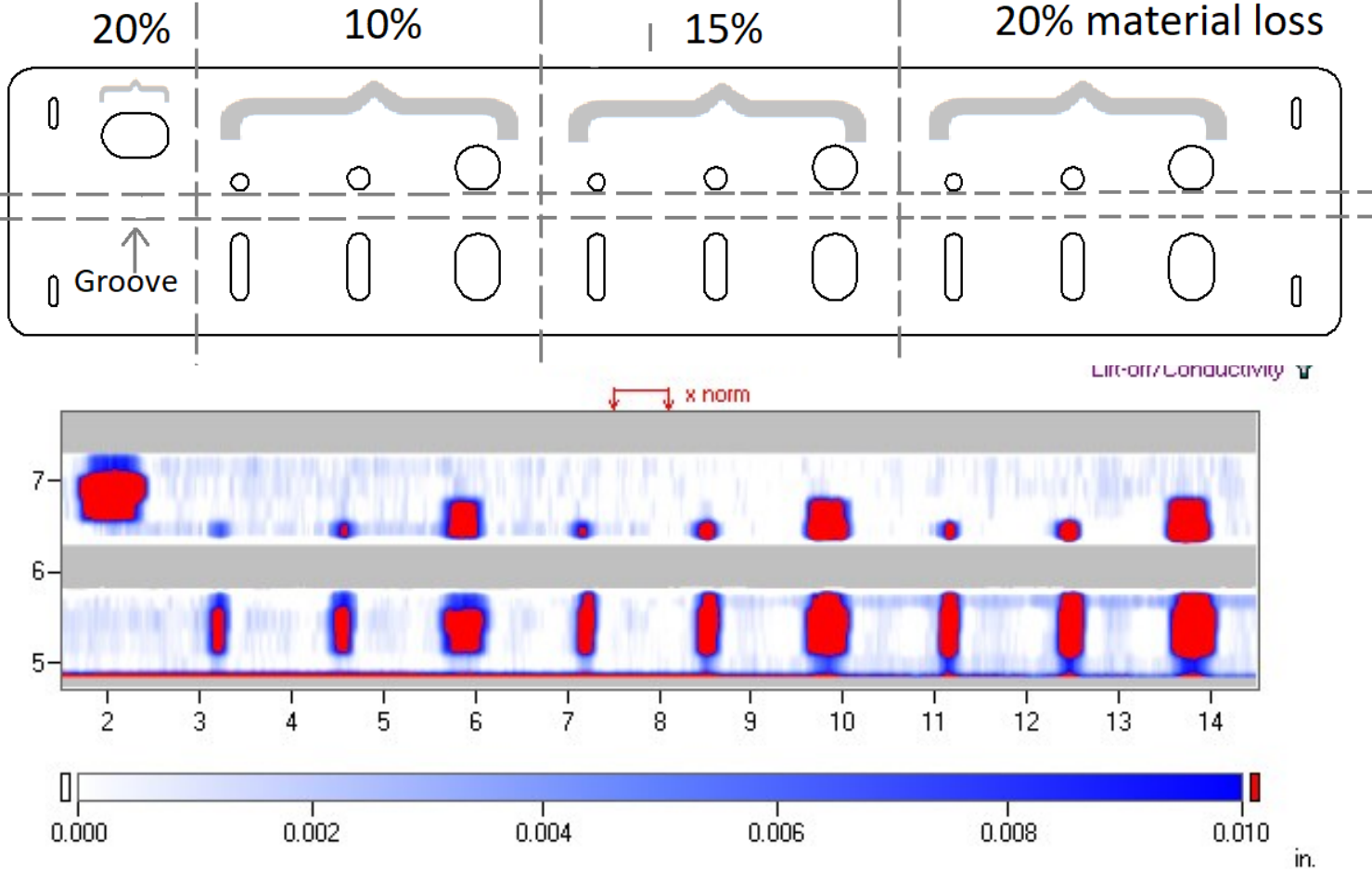
- FA258
- Detection of corrosion up to 0.060 in. 1<sup>st</sup> layer

## New MWM-Array Sensor

- FA296
- Operates at lower power
- Lower frequency operation
  - 2<sup>nd</sup> layer thickness measurement feasibility for thicker layers

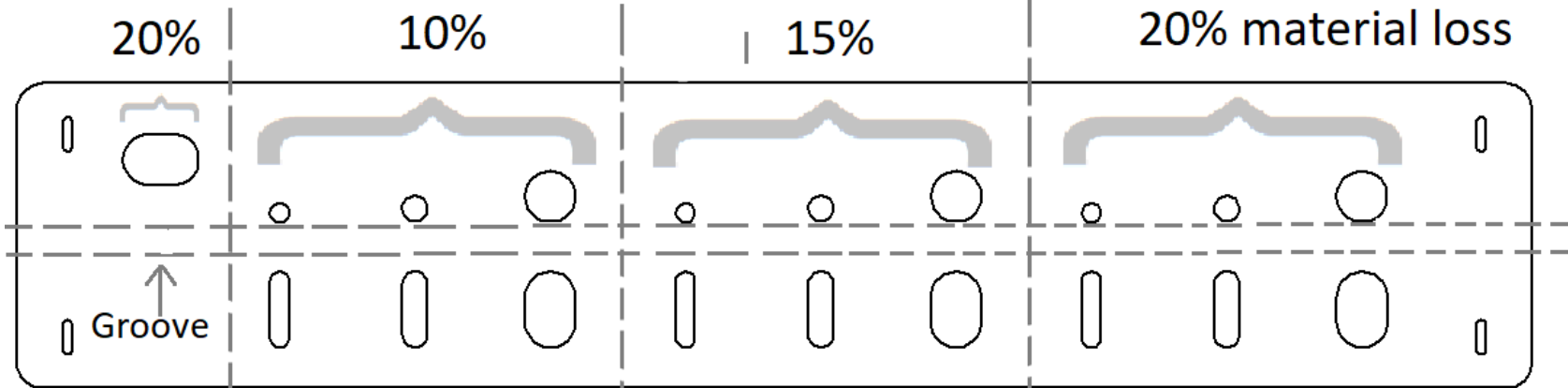


# FA296: 15 inch Corrosion Loss Sample (1)

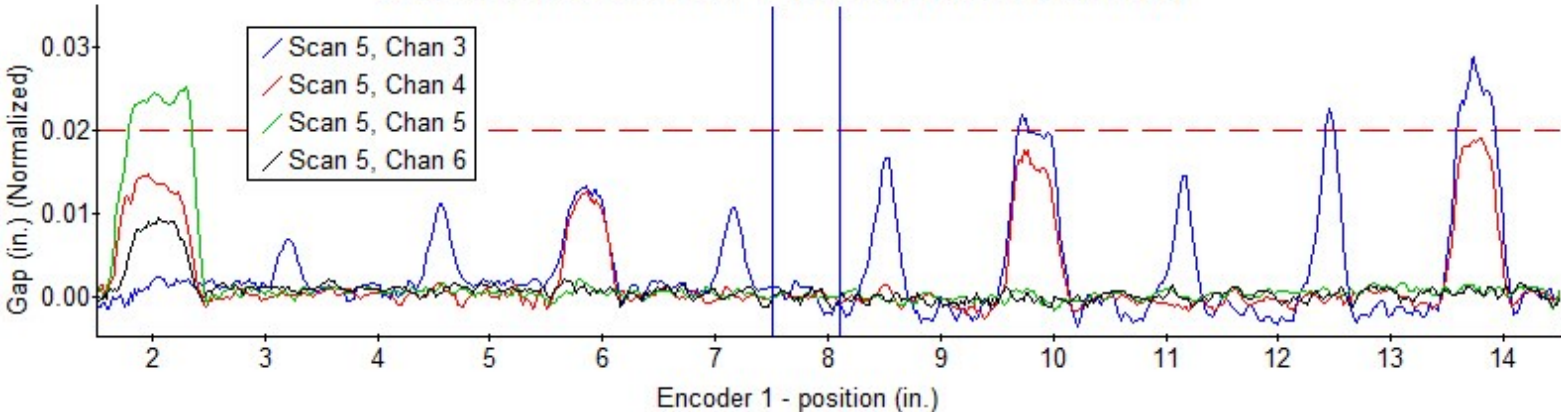


- Filtered and normalized C-scan of Gap data across the corrosion defect locations.

# FA296: 15 inch Corrosion Loss Sample Holes (2)

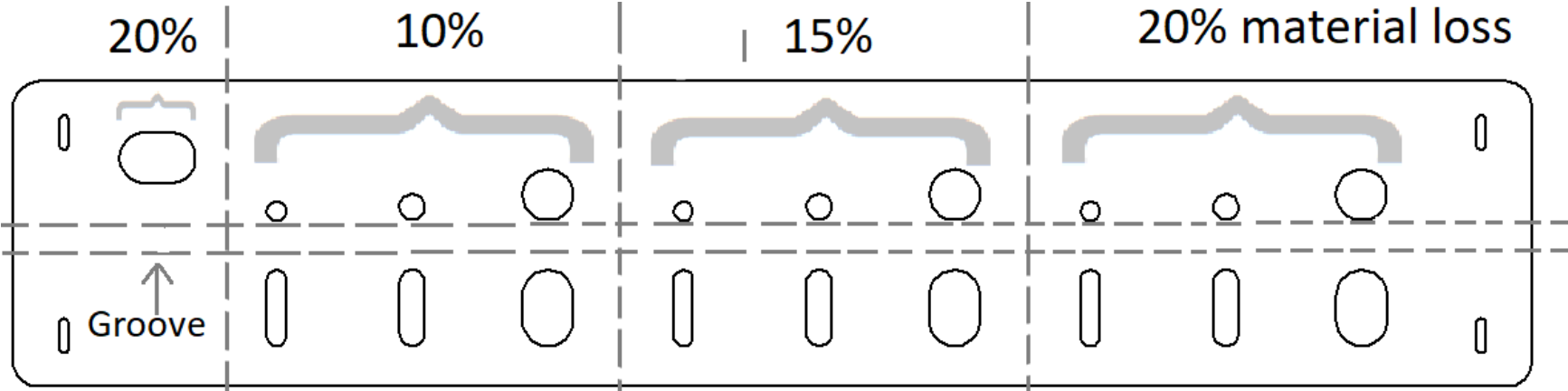


Step 2: Gap vs. Encoder 1 - position (Moving average)

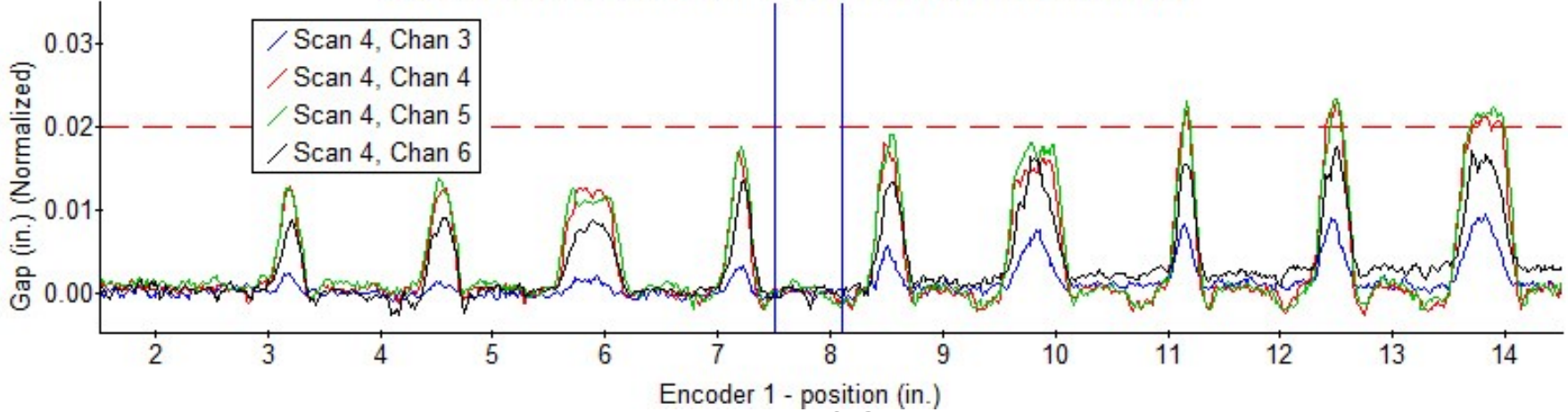


- Normalized B-scan of Gap data across the flat bottom hole defect locations.

# FA296: 15 inch Corrosion Loss Sample Slots (3)



Step 2: Gap vs. Encoder 1 - position (Moving average)

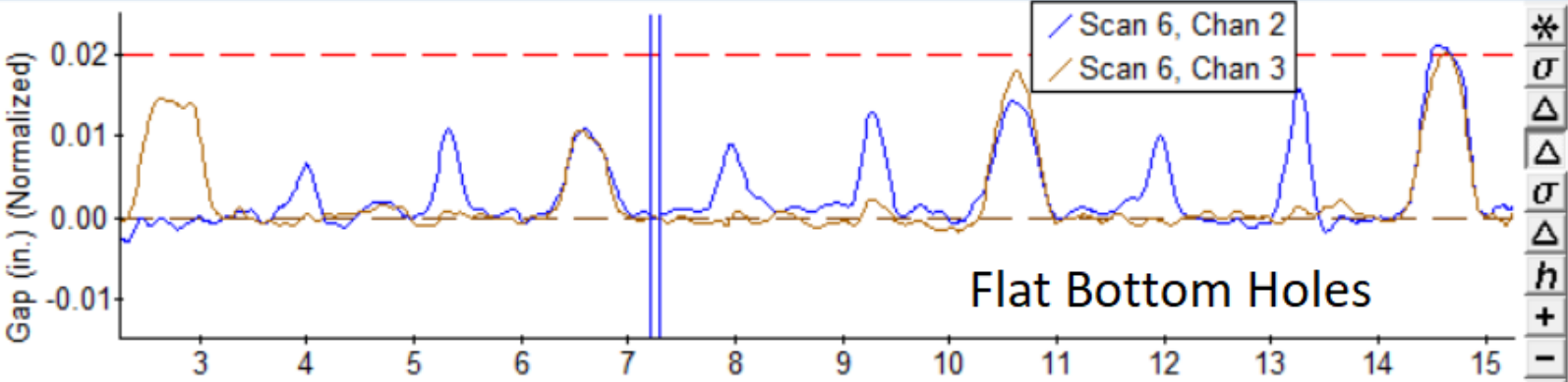


- Normalized B-scan of Gap data across the flat bottom slot defect locations.

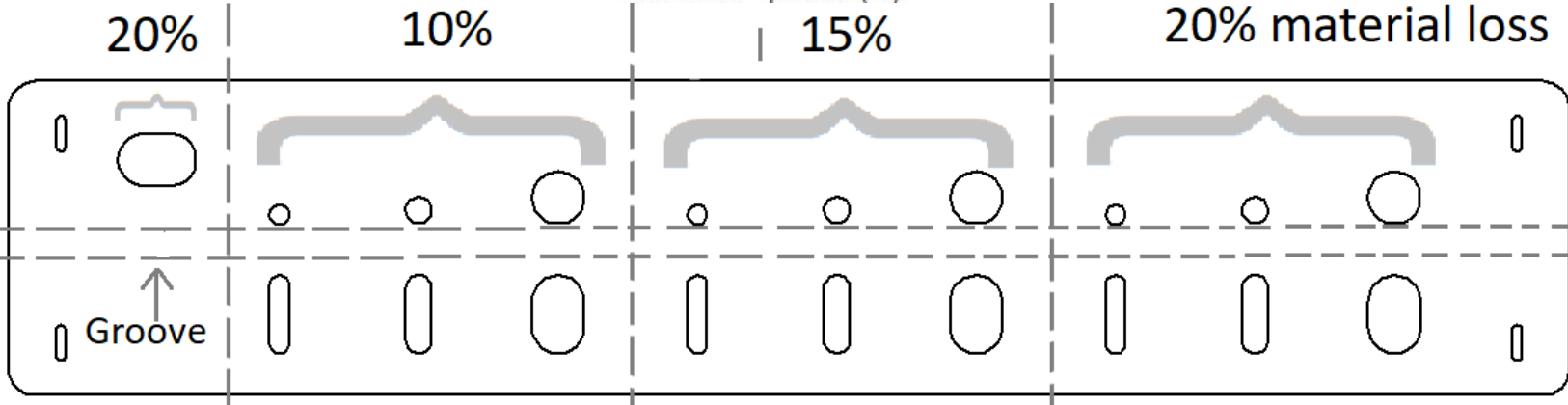
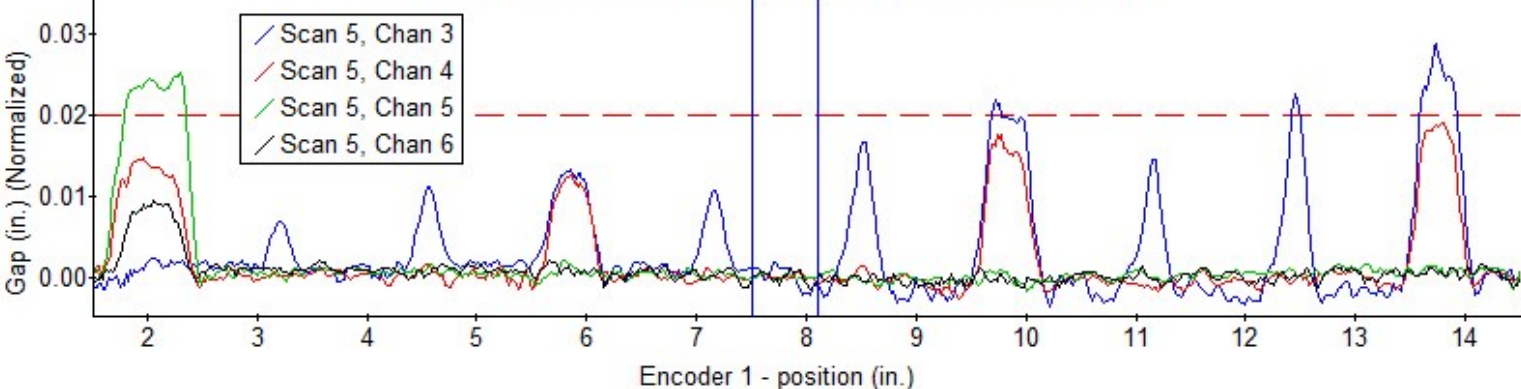


# Holes: FA258 at high power vs FA296 at low power

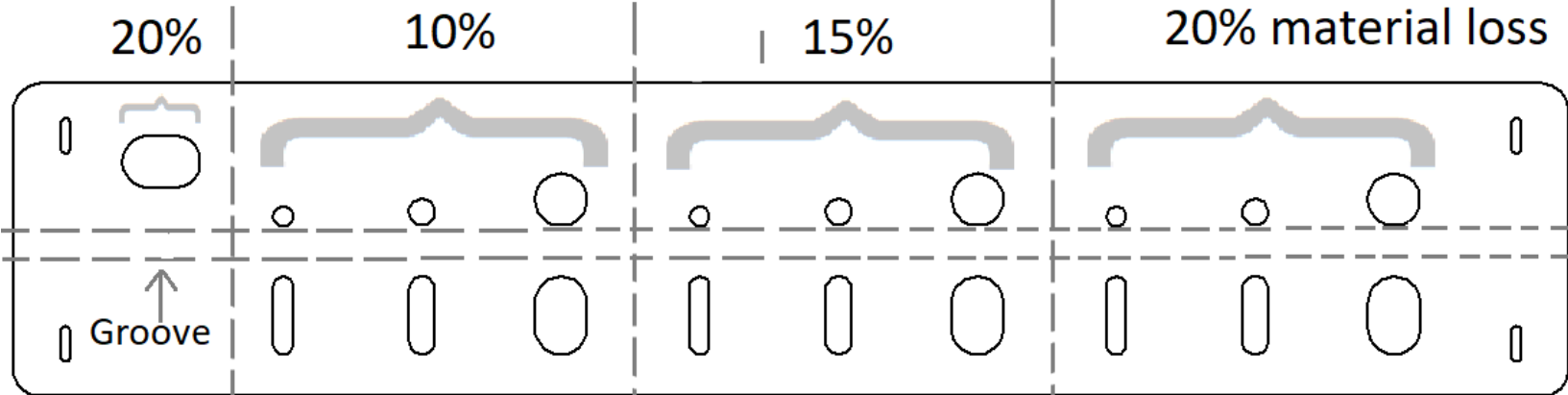
**FA258**



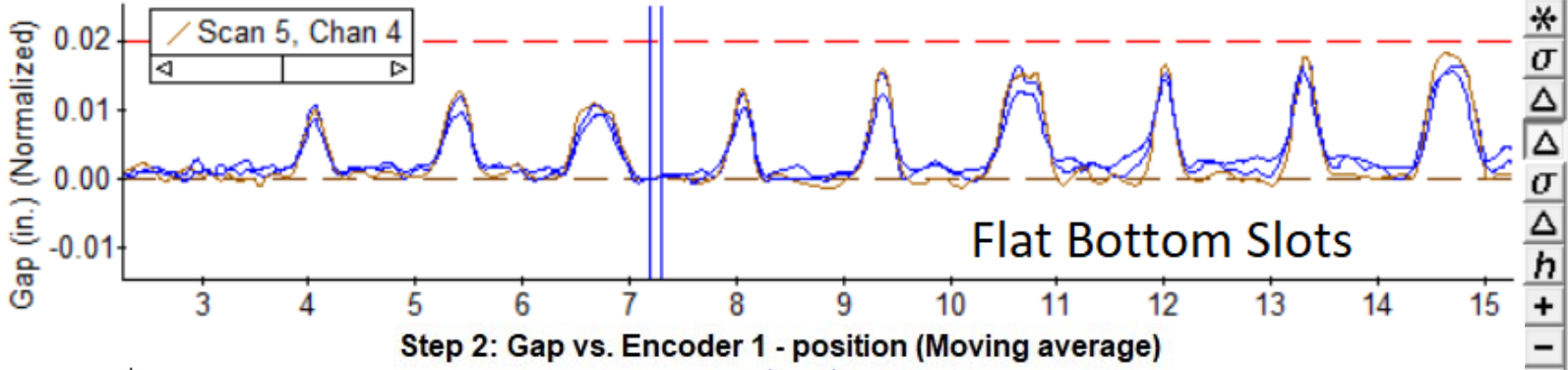
**FA296**



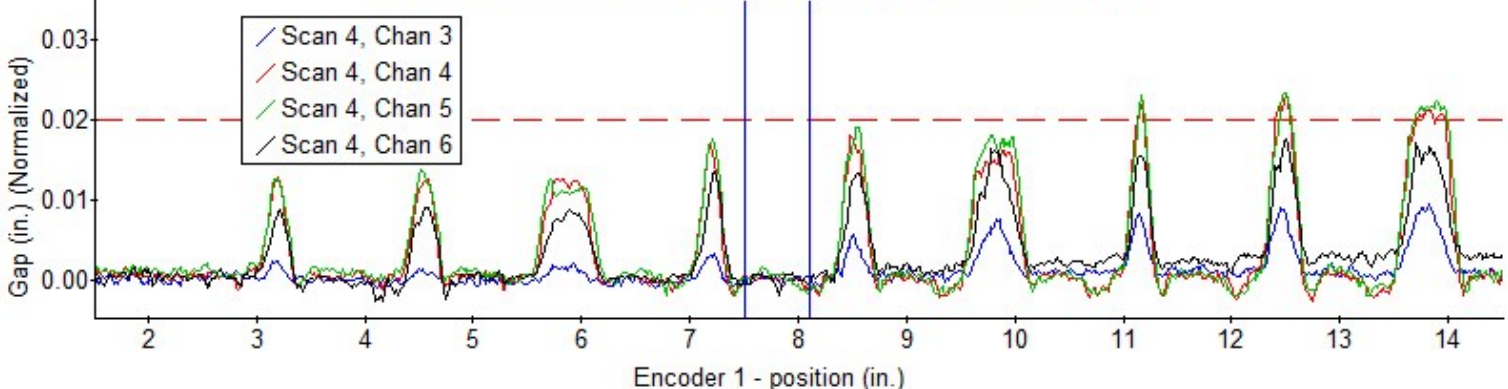
# Slots: FA258 at high power vs FA296 at low power



**FA258**



**FA296**





## Demonstrated Capability

- 2003 Demonstrated independent 1<sup>st</sup> and 2<sup>nd</sup> layer corrosion loss detection capability but system was slow and costly
- 2019 Demonstrated increased speed and improved ease-of-use and portability.

## Ongoing

- Improving portability of method for varied applications using augmented intelligence methods (jAI)
- Improving signal to noise to address second layer exfoliation detection, as well as improved wall loss sensitivity for thicker skins